



Solving a Production and Inventory Model with a Minimum Lot Size Constraint

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Abstract: The paper deals with the analysis of a special dynamic production and inventory model. In this model logical restrictions to fulfill an accepted constant minimal level of the production lot size are incorporated, instead of keeping setup cost in the objective function, as it is common in many other models. Detailed optimality conditions are derived, which make possible the application of a simple dynamic programming recursion procedure.

Keywords: dynamic production-inventory model, minimum lot size, dynamic programming

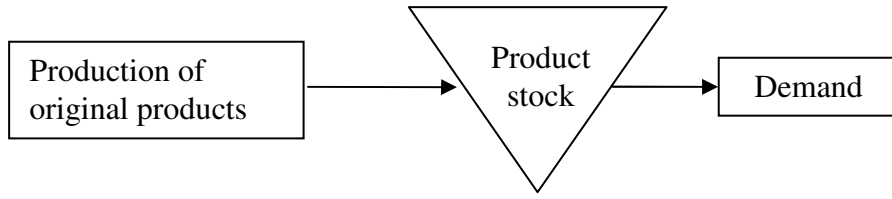
1. Introduction

In Richter and Gobsch (2005) a class of dynamic models of closed-loop logistics has been proposed in which the demand is satisfied by originally produced products as well as by re-manufactured used products. Apart from many other approaches (Minner and Lindner 2003, Richter and Sombrutzki 2000, Richter and Weber 2001, Golany, Yang, and Yu 2001, Beltrán and Krass 2002, etc.) the lot size is not determined by finding the minimum of the setup cost and holding cost but by minimizing the inventory cost subject to certain lot size restrictions. The special case of constant minimal lot size values and restricted return rates of an efficient dynamic programming algorithm has been presented which employs efficiently solvable combinatorial sub-problems. Since the main attention was paid to the problems of the closed-loop logistics, the algorithm was described rather shortly. In fact, the model described in that paper demands a two-dimensional dynamic programming procedure. Special assumptions on the backflow of used products, however, allow the reduction to a one-dimensional procedure. If the backflow is cut the dynamic problem with lot size restrictions to be studied here appears.

2. The basic problem with lot size restrictions

The process of producing a product for several periods of a planning horizon is considered. The items are produced during the periods according to the demand which occurs at the end of the periods. By accumulation of produced items stocks will be created and inventory cost appears (see Fig. 1).

Fig.1. *The basic problem*



The following symbols will be used below. The sets of integers, natural numbers and real numbers are denoted by I , $N = \{1,2,\dots\}$ and R , correspondingly. Furthermore, the following characters denote:

$T \in N$ – planning horizon consisting of T periods,

$D_t \in I$ – demand for the product in the t^{th} period, where $D_{i-1,t} = \sum_{j=i}^t D_j$, $D_{j,j} = 0$,

$H \in R$ – the per unit inventory cost for the product,

$m \in N$ – the minimal bound (level) of the positive lot size for the production process.

The variables are denoted by

I_t – inventory of final products at the end of the t^{th} period, $I_{i-1,t} = \sum_{j=i}^t I_j$ and

z_t – production rate of the t^{th} period $z_{i-1,t} = \sum_{j=i}^t z_j$.

Now the following model will be presented:

The inventory at the beginning and at the end of the planning horizon is set equal zero, e. g.

$$I_0 = I_T = 0. \quad (1)$$

The inventory of a new period equals the previous inventory plus the difference of production and demand:

$$I_t = I_{t-1} + z_t - D_t, I_t \geq 0, t = 1,2,\dots,T. \quad (2)$$

Due to the given minimal lot size bound the real lot sizes have to be either equal zero or not to be smaller than m . This condition is expressed by

$$z_t \in \{0\} \cup [m, +\infty[, t = 1,2,\dots,T. \quad (3)$$

Lot size restrictions of the similar structure were also considered in Beer, Käschel, and Richter (1979) as well as in Richter, Bachmann and Dempe (1988). Recent papers that consider minimum lot size constrains are, among others, Kallrath (1999), Suerie (2005) and Souza, Zhao, Chen, and Ball (2004).

The goal of minimizing the inventory cost is modeled by the objective function:

$$H \cdot \sum_{t=1}^T I_t \rightarrow \min . \quad (4)$$

Note that the condition (3) forbids the constellation $0 < z_t < m$, i.e. no lot sizes below the minimal level are allowed. In the objective function (4) the end of period inventories are multiplied by the cost factors and the whole expression is to be minimized. Since that cost factor is not significant for the study, it will be omitted, and the minimization of the total inventory will remain as the main goal.

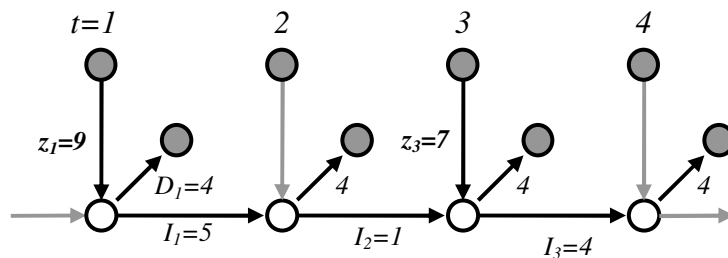
The entire model (1) – (4) has then the following compact form (5).

$$\begin{aligned} I_0 = I_T = 0, \\ z_t \in \{0\} \cup [m, +\infty[, \\ I_t = I_{t-1} + z_t - D_t, \quad I_t \geq 0, \quad t = 1, 2, \dots, T, \\ \sum_{t=1}^T I_t \rightarrow \min \end{aligned} \quad (5)$$

Example 1: Given the demand $D = (4, 4, 4, 4)$, $m = 7$. The solution No. 1 with two production periods shown in Fig. 2 is obviously feasible. The total inventory of this solution is $5 + 1 + 4 = 10$. This solution can be also presented graphically as in Fig. 3. The demand is shown by bold lines at the end of the periods, the productions quantities are represented by the marked areas and the inventories by grey areas.

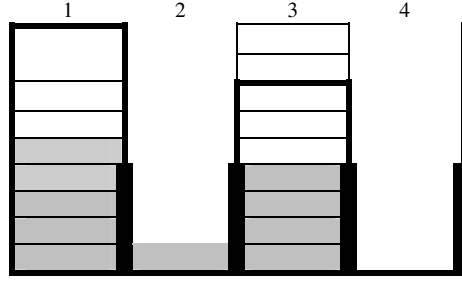
Better feasible solutions with the cost of $10 - 2\varepsilon$ units are given by the solutions No. 2(ε): $z_1 = 9 - \varepsilon, z_2 = 7 + \varepsilon, I_1 = 5 - \varepsilon, I_2 = 1 - \varepsilon, I_3 = 4, z_2 = z_4 = I_4 = 0$ for $0 \leq \varepsilon \leq 1$.

Fig. 2. The material flow for the solution No. 1 of example 1



The model (5) is obviously a linear program on a union of convex polyhedral sets. Hence an optimal solution can be found among the basis (extreme) solutions. The approach presented now will concentrate on the properties of basis solutions.

Fig. 3. The solution No. 1 of example 1



3. The Dynamic Programming Approach

3.1. Sub-problems with restricted lot sizes

The problem (5) will be denoted by $SP(0, T)$ and any sub-problem for selected periods $j = i, i+1, \dots, t$ with $I_{i-1} = I_t = 0, I_j \geq 0, j = i, \dots, t-1$ by $SP(i-1, t)$. It will be also said that a sub-problem is generated by the pair (i, t) . The corresponding minimum cost for an optimal basis solution of a solvable sub-problem will be denoted by $C_{i-1, t}$. The sub-problem $SP(i-1, t)$ is called *solvable (unsolvable)* if $D_{i-1, t} \geq m$ ($D_{i-1, t} < m$)

$$(6)$$

holds. A sub-problem $SP(i-1, t)$ is called *minimal*, if there is no period $i < k < t$ such that

$$(7)$$

It follows from the definition of the minimal sub-problem that the inventory values of an optimal solution are positive except for the last period.

An optimal basis solution of the problem (5) consists on a composition of optimal basis solutions for appropriate minimal sub-problems

$$SP(0, t_1), SP(t_1, t_2), \dots, SP(t_{L-1}, t_L), 1 \leq L \leq T. \quad (8)$$

The feasible basis solutions with positive inventories for the first example are given by $z_{0,4}^1 = (16, 0, 0, 0)$, $I_{0,4}^1 = (12, 8, 4, 0)$ and $z_{0,4}^2 = (7, 9, 0, 0)$, $I_{0,4}^2 = (3, 8, 4, 0)$ with the total inventory values 24 and 15, correspondingly. This example regarded as a sub-problem is not minimal, since the minimum is reached by $C_{0,2} + C_{2,4} = 8$.

Transformations: In the argumentation used below three types of transformation are applied all of which produce a new feasible solution with reduced total inventory.

$TI(j', j'')$: In this case there are given two production periods $j' < j''$

with $z_{j'} > z_{j''} \geq m$, $I_j > 0$, $j = j', \dots, j'' - 1$. Then the transformation

$$z_{j'} := z_{j'} - \varepsilon, z_{j''} := z_{j''} + \varepsilon, I_j := I_j - \varepsilon, j = j', \dots, j'' - 1 \text{ for } \varepsilon = \min\{z_{j'} - m, I_{j''-1}\} \quad (9)$$

will be applied.

$T2(j)$: There is a production period $j > i$ with $I_{j-1} \geq D_j$. Then the transformation

$$z_{j+1} := z_{j+1} + z_j, I_j := I_j - z_j, z_j = 0 \text{ will be applied.} \quad (10)$$

$T3(j)$: There is a production period $j < t$ with $z_j \geq 2m$ or $z_j = m$ and $I_j \geq m$. Then the

transformation $z_j := z_j - m$, $I_j := I_j - m$, $z_{j+1} := z_{j+1} + m$ will be applied. (11)

The transformations are illustrated by the examples 2 in Tab. 1.

Tab. 1. Examples 2 to illustrate the transformations $T1 - T3$

j	1	2	3	4	5	6	Total inventory
D_j	4	4	4	4	4	4	
z_j	7	10	0	0	7	0	$T1(2, 5)$
I_j	3	9	5	1	4	0	22
z_j	7	9	0	0	8	0	↓
I_j	3	8	4	0	4	0	19
z_j	7	10	0	7	0	0	$T2(4)$
I_j	3	9	5	8	4	0	29
z_j	7	10	0	0	7	0	↓
I_j	3	9	5	1	4	0	22
z_j	7	17	0	0	0	0	$T3(2)$
I_j	3	16	12	8	4	0	43
z_j	7	10	7	0	0	0	↓
I_j	3	9	12	8	4	0	36

Lemma 1: Let an optimal basis solution of a minimal sub-problem $SP(i-l, t)$ be given.

(i) Then there is no more than one period j' such that $z_{j'} > m$, i. e. $z_j \in \{0, m\}$, $j \neq j'$. (12)

(ii) Such a period is the last production period for an optimal solution.

Proof: (i) Let an optimal basis solution be given with $j' < j''$ and

$z_{j'}, z_{j''} > m$, $I_j > 0$, $j = j', \dots, j'' - 1$. Then the transformation $T1(j', j'')$ can be applied which shows that the initial solution is not optimal or the sub-problem is not minimal.

(ii) In the case when $z_{j'} > m$ and there is a production period j'' after j' , the application of $T1(j', j'')$ would reveal that the solution is not optimal.

If an optimal basis solution contains a period j' with $z_{j'} > m$, or if j' is the last production period with $z_{j'} = m$, the periods $j < j'$ for which $z_j = 0 \vee m$ hold will be called *extreme pro-*

duction periods. The periods $j > j'$, for which the values are equal zero i. e., $z_j = 0$, are called *zero production periods*.

3.1.1. Real sub-problems

A sub-problem will be called *real* if from the existence of a period $j^* = \min\{j \geq i : D_{i-1,j} = l \cdot m, l \leq j - i + 1, l \in N\}$ it follows that $D_{j^*,t} < m$. (13)

If there is no such period then the problem is always real.

That means, provided a period j^* exists, then for a real sub-problem $D_{i-1,t} < (l+1) \cdot m$ holds:

Lemma 2: If a sub-problem $SP(i-l, t)$ is minimal then it is real.

Proof: Let an optimal basis solution of a minimal sub-problem be given which is not real, i.e. there is a period j^* and $D_{j^*,t} \geq m$ holds. Let two cases be studied.

(i) If $z_j = 0 \vee m, j = i, i+1, \dots, j^*$ then either $I_{j^*} = 0$ holds or $I_{j^*} \geq m$. In the first case the sub-problem is not minimal, i.e. $C_{i-1,t} = C_{i-1,j^*} + C_{j^*,t}$. In the second case, due to $D_{j^*,t} \geq m$, the transformation $T3(j)$ can be applied to the last production period $j' \leq j^*$ and hence the initial solution is not optimal.

(ii) There is a production period $j^+ \leq j^*$ with $z_{j^+} > m$. Then according to Lemma 1 this is the last production period. Hence $z_j = 0 \vee m$ holds for $j < j^+$. Then due to the assumption of the proof the relation $I_{j^+} = D_{j^+,t} \geq m$ holds. Now two cases can be distinguished:

(α) If $z_{j^+} > 2m$ then the transformation $T3(j)$ can be applied for $j = j^+$.

(β) Let $z_{j^+} < 2m$. Then due to the definition of a real sub-problem (13) there is an integer $l > 0$ such that $l \cdot m = D_{i-1,j^*}$. It will be proved now that the number of production periods with $z_j = m$ before j^+ is not less than the number l . If this is not true then $z_{i,j^+-1} + z_{j^+} < (l-1)m + 2m = D_{i-1,j^*} + m \leq D_{i-1,t}$ holds, i.e. the whole demand will not be satis-

fied. Then $z_{i,j^+-1} \geq l \cdot m = D_{i-1,j^*}$ and $I_{j^+-1} = z_{i-1,j^+-1} - D_{i-1,j^+-1} \geq D_{j^+-1,j^*} \geq D_{j^+}$ hold.

That means that the transformation $T2(j)$ can be applied for $j = j^+$. \square

Corollary: A real sub-problem is not necessarily minimal! Example 1 is real but not minimal.

3.1.2. Critical period

Below only minimal sub-problems will be analyzed. First, the following parameters and remarkable periods are introduced:

$$\text{Let's introduce the integers } k_{i-1,j} = \left\lfloor \frac{D_{i-1,j}}{m} \right\rfloor, k_{i,i} = -1. \quad (14)$$

$$\text{Provided, the relations } D_{i-1,l} < m \cdot (l - i + 1), l = i, i+1, \dots, j, j < j^*, \quad (15)$$

hold, the number $k_{i-1,j} + 1$ is the minimal number of production periods of size m satisfying this demand. Since only one production figure can be larger than m , the number $k_{i-1,t}$ shows how many productions periods are needed to satisfy the whole demand of the sub-problem.

$$\text{Let the period } j^\# = \min\{j \geq i : D_{i-1,j} > (j - i + 1) \cdot m\} \quad (16)$$

be the first period where the relation (15) is strongly violated.

$$\text{If the relations (15) hold, the critical period } j_{i-1,t} = \min\{j \geq i : D_{i-1,j} > (k_{i-1,t} - 1) \cdot m\} \quad (17)$$

is such a period the demand of which cannot be satisfied fully by $k_{i-1,t} - 1$ production periods of size m . Therefore it is the last production period with a production figure equal or larger than m . Alternatively, the definition $j_{i-1,t} = \min\{j \geq i : k_{i-1,j} = k_{i-1,t} - 1\}$ (18)

can be used.

Another period which is important for the analysis is

$$j^\times = \min\{j \geq i : k_{i-1,j} - k_{i-1,j-1} > 1\}. \quad (19)$$

If the periods j^* , $j^\#$ or j^\times do not exist they will be set equal $t + 1$, correspondingly.

Lemma 3: Let a real sub-problem $SP(i-1, t)$ be given.

(i) Then $j_{i-1,t} \leq j^*$ and

(ii) if a period $j^\#$ exists then $D_{j^\#} > m$ and $j^\# \leq j^*$ holds and it coincides with j^\times . (20)

Proof: (i) Let $j_{i-1,t} > j^*$. Then due to the definition (17) the relation $D_{i-1,j^*} \leq (k_{i-1,t} - 1) \cdot m$ and the inequality $D_{i-1,j^*} + m \leq k_{i-1,t} \cdot m \leq D_{i-1,t}$ hold. It follows from the last inequality that $D_{j^*,t} \geq m$, what contradicts the assumption.

(ii) Let now a period $j^\# > i$ exist. Then due to the definition (16) the relation $D_{j^\#} = D_{i-1,j^\#} - D_{i-1,j^\#-1} > (j^\# - i + 1)m - (j^\# - i)m = m$ holds and the demand $D_{j^\#}$ is larger than m . If there is a period j^* , then the relation $t \leq m(j^*)$ holds. Then the case $j^\# > j^*$ is not possible due to $D_{j^\#} > m$, i.e. $j^\# \leq j^*$ holds. It follows from this property and

from the definition (16) that $D_{i-1,j^\#-1} < (j^\# - i) \cdot m$ and $\left\lfloor \frac{D_{i-1,j^\#-1}}{m} \right\rfloor \leq j^\# - i - 1$. Based on

this inequality the following estimation can be given:

$$k_{i-1,j^\#} - k_{i-1,j^\#-1} = \left\lfloor \frac{D_{i-1,j^\#}}{m} \right\rfloor - \left\lfloor \frac{D_{i-1,j^\#-1}}{m} \right\rfloor \geq j^\# - i + 1 - (j^\# - i - 1) = 2, \text{ by which the}$$

equality $j^\# = j^\times$ is proved. If $j^\# = i$ then the statement holds per definition. \square

Corollary: Since due to Lemma 2 minimal sub-problems are real Lemma 3 holds for such problems, too.

Tab. 2: Example 3 of a real (minimal) sub-problem with $m=7$, $k_{0,6} = 4$, $j^\# = j^\times = 4$, since

$$D_{0,3} = 18 < 4 \cdot 7 < 29 = D_{0,4} \text{ and } k_3 = 2 < 4 = k_4$$

j	1	2	3	4	5	6	Total inventory
D_j	6	6	6	11	2	2	
$k_{0,j}$	0	1	2	4			
z_j	7	7	7	12	0	0	
I_j	1	2	3	4	2	0	12
z_j	7	11	0	15	0	0	
I_j	1	6	0	4	2	0	13

Lemma 4: Let a sub-problem $SP(i-1,t)$ be given with a period $j^\#$.

(i) If the sub-problem is real and $D_{j^\#,t} < m$ then $j^\# = j_{i-1,t}$ and

(ii) if it is minimal then $D_{j^\#,t} < m$ and $j^\# = j_{i-1,t}$.

Proof: If the sub-problem is real and a period $j^\#$ exists, then it follows from Lemma 3 that

$j^\# \leq j^*$. Moreover, $D_{j^*,t} < m$ and $D_{i-1,t} \geq k_{i-1,t} \cdot m$ hold. Then $D_{i-1,j^*} = D_{i-1,t} - D_{j^*,t} > (k_{i-1,t} - 1) \cdot m$ and $j^* \geq j_{i-1,t}$.

$$(i) \text{ Let } D_{j^\#,t} < m. \text{ Then } k_{i-1,j^\#} = \left\lfloor \frac{D_{i-1,t} - D_{j^\#,t}}{m} \right\rfloor \geq k_{i-1,t} - 1 \text{ holds.} \quad (21)$$

It will be proved that $j^\# \neq j_{i-1,t}$ will lead to contradictions.

First, the case $j^* \geq j_{i-1,t} > j^\#$ will be analyzed. Then due to the definition (17) $D_{i-1,j^\#} < (k_{i-1,t} - 1)m$ and due to relation (21) the contradicting inequalities $k_{i-1,j^\#} < k_{i-1,t} - 1 \leq k_{i-1,j^\#}$ hold.

Secondly, let the case $j_{i-1,t} < j^\# \leq j^*$ be considered. Then due to the definition (16) the relation $D_{i-1,j_{i-1,t}} < (j_{i-1,t} - i + 1)m \leq (j^\# - i)m$ holds. Due to this inequality and the definition (18) the relation $k_{i-1,j_{i-1,t}} = k_{i-1,t} - 1 < j^\# - i$ occurs. Due the definition (16) also $j^\# - i + 1 \leq k_{i-1,j^\#} \leq k_{i-1,t}$ holds that leads to the contradiction $k_{i-1,t} < j^\# - i + 1 \leq k_{i-1,t}$.

Hence the first statement is true, i.e. $j^\# = j_{i-1,t}$.

(ii) Because of Lemma 2 this case is fulfilled for $D_{j^\#,t} < m$ automatically. For $D_{j^\#,t} \geq m$ it will be proved that the sub-problem is not minimal. Let an optimal basis solution be given. Since $j^\# - i + 1$ production runs of size m do not satisfy the demand $D_{i-1,j^\#}$, the production rate at the period $j^\#$ will fulfill $z_{j^\#} > m$. Then due to Lemma 1 this is the last production period at all and $z_{j^\#} = D_{i-1,j^\#} + D_{j^\#,t} - z_{i-1,j^\#-1} > (j^\# - i + 1)m + m - (j^\# - i)m = 2m$. Furthermore, the estimate $I_{j^\#} = D_{j^\#,t} \geq m$ holds and, the transformation $T3(j)$ can be applied. Hence the case (ii) is not valid for minimal sub-problems. \square

Lemma 5: Let a sub-problem $SP(i-1,t)$ be given with a period j^\times .

(i) If the sub-problem is real and $D_{j^\times,t} < m$ then $D_{j^\times} > m$, $j^\times \leq j^*$ and $j^\times = j_{i-1,t}$ and,

(ii) if it is minimal then $D_{j^\times,t} < m$, $D_{j^\times} > m$, $j^\times \leq j^*$ and $j^\times = j_{i-1,t}$. (22)

Proof: If a period $j^\#$ exists, Lemmas 3 and 4 can be applied for both cases.

(i) Let $D_{j^\times,t} < m$. Then, as in the proof of Lemma 4 (see formula (21)) the relation

$$k_{i-1,j^\times} = \left\lfloor \frac{D_{i-1,t} - D_{j^\times,t}}{m} \right\rfloor \geq k_{i-1,t} - 1 \text{ holds.} \quad (23)$$

Further, it follows from $k_{i-1,j^\times} - k_{i-1,j^\times-1} \geq 2$ that $D_{j^\times} > m$. Hence as in the proof of Lemma 3 the inequality $j^\times > j^*$ is not possible.

First, let $j_{i-1,t} < j^\times \leq j^*$. Then $k_{i-1,j_{i-1,t}} < k_{i-1,j^\times} - 1$ and $D_{i-1,j_{i-1,t}} \leq (k_{i-1,t} - 1)m$ hold.

That is, however, a contradiction to the definition (17).

Secondly, let $j^\times < j_{i-1,t} \leq j^*$. Then $D_{i-1,j_{i-1,t}} > (k_{i-1,t} - 1)m$, $D_{i-1,j^\times} < (k_{i-1,t} - 1)m$ and $k_{i-1,j^\times} < k_{i-1,t} - 1$. That is a contradiction to formula (23). Hence the first statement concerning $j^\times = j_{i-1,t} \leq j^*$ is true.

(ii) For the case of $D_{j^\times,t} \geq m$, it will be proved that in this case the sub-problem is not minimal. Because of the assumption the sub-problem is real and the situation $j^\times > j^*$ is not possible due to $D_{j^\times} > m$. The equality $j^\times = j^*$ is not possible either, because of the assumption on (ii). Hence $j^\times < j^*$. Note, that in this case $k_{i-1,j^\times} < k_{i-1,t}$ holds. Now let some optimal basis solution be given.

First, let $z_{j^\times-1,t} = 0$. Then, since $D_{j^\times} > m$ and $D_{j^\times,t} \geq m$ there is some closest period $j' < j^\#$ with $z_{j'} \geq m$ and $I_{j'} \geq D_{j^\times-1,t} > 2m$. If $z_{j'} \geq 2m$ then the transformation $T3(j)$ can be applied. Let $z_{j'} < 2m$. Then $2m < I_{j'} = I_{j'-1} + z_{j'} - D_{j'} < I_{j'-1} + 2m - D_{j'}$ and, $D_{j'} < I_{j'-1}$ and, the transformation $T2(j)$ can be applied.

Secondly, if $z_{j^\times} = 0$, $z_{j^\times,t} > 0$ then there exists a closest period $j' < j^\times$ with $z_{j'} = m$ and $I_{j'} > m$. Then again the transformation $T3(j)$ can be applied.

Thirdly, if $z_{j^\times} \geq m$, $z_{j^\times,t} = 0$ then either $z_{j^\times} \geq 2m$, $I_{j^\times} \geq m$ or $z_{j^\times} < 2m$, $I_{j^\times} \geq m$. In the first case the transformation $T3(j)$ can immediately be applied to the period j^\times . For the second case, it can be noticed that the inequalities $k_{i-1,j^\times-1} + 2 \leq k_{i-1,j^\times} \leq k_{i-1,t} - 1$,

$k_{i-1,j^\times-1} \leq k_{i-1,t} - 3$ and $D_{i-1,j^\times-1} \leq (k_{i-1,t} - 2) \cdot m$ hold. Furthermore the relations $z_{i-1,j^\times-1} + z_{j^\times} \geq k_{i-1,t} \cdot m$ and $-z_{j^\times} > -2m$ hold, i.e. $z_{i-1,j^\times-1} > (k_{i-1,t} - 2) \cdot m$ is fulfilled. Since $z_{i-1,j^\times-1}$ is a multiple of m , actually $z_{i-1,j^\times-1} \geq (k_{i-1,t} - 1) \cdot m$ holds. This means that $I_{j^\times-1} = z_{i-1,j^\times-1} - D_{i-1,j^\times-1} \geq m$ is true and the transformation $T3(j)$ can be applied to the last positive production period before j^\times . \square

Lemma 5 is illustrated by the example 4 in Tab. 3. The solution with $D_{j^\times,t} \geq m$, $z_{j^\times} > 2m$ and $I_{j^\times} > m$ is transformed by $T3(j)$ and, a better solution appears as a composition of solutions for $SP(i-1, j^\times)$ and $SP(j^\times, t)$.

Tab. 3: Example 4 with $m=7, k_{0,6} = 3, j^\times = 4$

j	1	2	3	4	5	6	Total
D_j	2	2	2	9	4	4	inventory
$k_{0,j}$	0	0	0	2			
z_j	7	0	0	16	0	0	
I_j	5	3	1	8	4	0	21
z_j	7	0	0	8	8	0	↓
I_j	5	3	1	0	4	0	13

Corollary: It can be seen that if such period j^\times will be found then it will be always the last production period for a minimal sub-problem.

3.1.3. Critical solution

Now the following components of a basis solution for minimal sub-problems can be determined by means of the parameters (14) and (19):

$$I_j^* = (k_{i-1,j} + 1) \cdot m - D_{i-1,j}, \quad z_j^* = I_j^* + D_j - I_{j-1}^* \text{ for } j < j_{i-1,t} \quad (24)$$

$$\text{and } z_{j_{i-1,t}}^* = D_{j_{i-1,t}-1,t} - I_{j_{i-1,t}-1}^*, \quad z_j^* = 0, j > j_{i-1,t}, I_j^* = D_{j,t}, j \geq j_{i-1,t}. \quad (25)$$

The basis solution (24) – (25) will be called *critical*. The total inventory provided by the critical solution is denoted by $C_{i-1,t}^*$.

Lemma 6: Let a sub-problem $SP(i-1, t)$ for given period i be regarded with $t = t_i$ and

$$t_i = \min\{m(j^\#), m(j^*), m(j^\times)\}, \quad (26)$$

where $m(j) = \max\{r : D_{j,r} < m\}$. Then the problem is real and the critical solution is feasible.

Proof: Because of the assumption (26) the sub-problem is real. Then Lemma 3 holds and $j_{i-1,t} \leq j^*$ is fulfilled and, due to the definition (13) the relation $k_{i-1,j} \cdot m < D_{i-1,j} < (k_{i-1,j} + 1) \cdot m$ holds for $j = i, i+1, \dots, j_{i-1,t} - 1$. It follows from these inequalities that the inventory values (24) are valid, i.e. the strong inequalities $I_j^* = (k_{i-1,j} + 1) \cdot m - D_{i-1,j} > 0, j < j_{i-1,t}$ hold. In case of the existence of a period $j^\#$ the latter is equal $j_{i-1,t}$ and $j^\# \leq j^*$. That means that $D_{i-1,j} < (j-i+1) \cdot m$ and $k_{i-1,j} + 1 \leq j-i+1, j < j^\#$, i.e. the number of production periods is not greater than the number of periods.

$$\text{According to (24) the equality } z_j^* = I_j^* + D_j - I_{j-1}^* = (k_{i-1,j} - k_{i-1,j-1}) \cdot m \quad (27)$$

holds. If there is a period j^\times then due to Lemma 5 it is equal $j_{i-1,t}$ and therefore $k_{i-1,j} - k_{i-1,j-1} \leq 1$, i.e. the production figures are equal zero or m . Furthermore, it follows from the definitions (24) – (25) and the inequality $D_{i-1,j_{i-1,t}-1} < (k_{i-1,t} - 1) \cdot m < D_{i-1,j_{i-1,t}}$

that $k_{i-1,j_{i-1,t}-1} + 1 \leq k_{i-1,t} - 1$ and that $z_{j_{i-1,t}}^* = D_{j_{i-1,t}-1,t} - I_{j_{i-1,t}-1}^* =$
 $= D_{j_{i-1,t}-1,t} + D_{i-1,j_{i-1,t}-1} - (k_{i-1,j_{i-1,t}-1} + 1) \cdot m \geq D_{i-1,t} - k_{i-1,t} \cdot m + m \geq m$, i.e. the production figure at the critical period is feasible. \square

Now it will be shown that the critical solution is also optimal.

Theorem 1: Let a minimal sub-problem be given. Then the critical solution is optimal.

Proof: (i) Due to Lemma 1 an optimal solution has a last production period whose production figure can be larger than m . Therefore there is a period $J_{i-1,t}$ as the last production period and the periods before $J_{i-1,t}$ are extreme production periods and the periods after $J_{i-1,t}$ are zero production periods per definition. The inventories values for the periods after $J_{i-1,t}$ are obviously given by $I_j = D_{j,t}, j = J_{i-1,t}, \dots, t$. Now some more properties of optimal solutions will be proved.

(ii) It will be shown that for an optimal solution the relation $z_j > 0$ implies $I_{j-1} < \min\{m; D_j\}$, or equivalently $I_{j-1} \geq \min\{m; D_j\}$ implies $z_j = 0$. Let j be the first period with $z_j > 0$ and $I_{j-1} \geq \min\{m; D_j\}$.

(iia) If $m \leq D_j$, and $I_{j-1} \geq m$ then $j > i$. Then there is a nearest production period $j' < j$ for which due (i) $z_{j'} = m$ holds. Since the sub-problem is also real, due to Lemma 2, the inventory value cannot be equal m and, it is therefore strongly larger than m , i.e. $I_{j-1} > m$ holds. Then the relation $I_{j'} = D_{j',j-1} + I_{j-1} > D_{j',j-1} + m$ holds and the transformation $T3(j)$ can be applied to the period j' .

(iib) If $m > D_j, z_j > 0$ and $I_{j-1} \geq D_j$, then the transformation $T2(j)$ can be applied.

(iii) Now it will be shown that $I_{J_{i-1,t}} < \max\{2m; 3m - D_{J_{i-1,t}}\}$. Let $j = J_{i-1,t}$ and, on the opposite, $I_j \geq \Delta = \max\{2m; 3m - D_j\}$ and $z_j \geq m$.

(iiia) If $D_j > m$, i.e. $\Delta = 2m$ and $2m \leq I_j = I_{j-1} + z_j - D_j$, then due to (ii) $2m < m + z_j - D_j$ holds and $2m < D_j + m < z_j$. Then the transformation $T3(j)$ can be applied to the period $j = J_{i-1,t}$.

(iiib) If $D_j \leq m$, i.e. $\Delta = 3m - D_j$, then due to (ii) $3m - D_j \leq I_j < m + z_j - D_j$ holds and $2m < z_j$. That means that the same transformation can be applied!

(iv) Finally, it will be shown that $J_{i-1,t} = j_{i-1,t}$ and that the inventory values for the extreme production periods are given by $I_j = I_j^*$, i.e. the optimal solution coincides with the critical solution. The critical solution is feasible due to Lemma 6.

(iva) Let now $I_j < I_j^*$ be fulfilled for some period $j \leq J_{i-1,t}$. Then, however, there is at least one production period less, i.e., $I_j \leq k_{i-1,j} \cdot m - D_{i-1,j} < 0$ holds and the solution is not feasible.

(ivb) If $I_j > I_j^*$ holds for a first production period j , there is at least one production period more and $I_j \geq (k_{i-1,j} + 2) \cdot m - D_{i-1,j}$ and $I_{j-1} = (k_{i-1,j-1} + 1) \cdot m - D_{i-1,j-1}$. Then $I_j \geq m$ and $D_{j,t} \geq m$ holds. Due to Lemma 5(ii) then $j < j^{\times} \leq j^*$ holds.

Then one of the two options is fulfilled: a) $k_{i-1,j} = k_{i-1,j-1}$ or, b) $k_{i-1,j} = k_{i-1,j-1} + 1$.

In the case a) per definition (14) $D_{i-1,j} < k_{i-1,j-1} \cdot m$, $D_j < m$ and,

$$I_j \geq (k_{i-1,j-1} + 2) \cdot m - D_{i-1,j} > 2m \text{ holds.}$$

If a1) $j = J_{i-1,t}$ then this is a contradiction to the statement (iii).

If a2) $j < J_{i-1,t}$ then $z_j = m$ and $I_{j-1} = I_j - z_j + D_j > D_j$ which is a contradiction to (ii).

In the case b) $I_j = I_{j-1} + z_j - D_j \geq (k_{i-1,j-1} + 3) \cdot m - D_{i-1,j-1} - D_j = I_{j-1} + 2m - D_j$ holds, or $z_j \geq 2m$. Then, however $j = J_{i-1,t}$.

Hence $I_j = I_j^*$ holds for $j \leq J_{i-1,t}$. Then $J_{i-1,t} = j_{i-1,t}$ since the critical solution cannot contain another production period. \square

Remark: It follows from the previous statements that for a given period i the maximal length of a minimal sub-problem can be estimated by (26). Therefore the feasible pairs (i, t) which generate minimal sub-problems belong to the set

$$X = \{(i, t) : i < t \leq t_i, (m(t) < T \vee t = T), (i = 1 \vee i > m(0))\}. \quad (27)$$

Due to the Lemma 6 sub-problems defined on elements from set X are real and the critical solution is feasible.

3.2. Solution algorithm

The approach presented here utilizes the ideas of dynamic programming and is illustrated by the example 5 in Tab. 4.

Let F_t be the minimal cost for the first t periods. Furthermore, let $F_0 = 0$. An optimal solution for the problem (5) can be found by the recursion

$$F_t = \min_{(i,t) \in X} \{C_{i-1,t}^* + F_{i-1}\} = C_{i(t)-1,t}^* + F_{i(t)}. \quad (28)$$

Detailed algorithm:

$$\begin{aligned} &F_0 := 0; \text{ For } t := 1 \text{ until } T \text{ do } F := +\infty; \\ &\text{ For } i := 1 \text{ until } t \\ &\text{ do if } (i, t) \in X \text{ and } F > F_{i-1} + C_{i-1,t}^* \\ &F := F_{i-1} + C_{i-1,t}^*; i(t) := i \text{ end; end} \end{aligned} \quad (29)$$

Lemma 7: The algorithm (29) generates an optimal solution as a series of optimal solutions of minimal sub-problems.

Proof: First, it will be proved that the pairs $(i(t), t)$ generate minimal sub-problems. If this is not true then there are two first periods t and i_l such that $C_{i(t)-1,t}^* \geq C_{i(t)-1,i_l}^* + C_{i_l-1,t}^*$. (30)

Due to the definition of $i(t)$ the inequality $F_{i(t)} + C_{i(t)-1,t}^* < F_{i_l} + C_{i_l-1,t}^*$ holds. Furthermore the relation $F_{i_l} \leq F_{i(t)} + C_{i(t)-1,i_l}^*$ holds and

$$F_{i(t)} + C_{i(t)-1,t}^* < F_{i(i)} + C_{i(i)-1,i_l}^* + C_{i_l-1,t}^*. \text{ This is a contradiction to inequality (30).}$$

Secondly, it will be proved that minimal total inventory for a problem over the first t periods is given by the value F_t . The sub-problem $SP(0, m(0)+1)$ is obviously minimal and it has the critical solution $z_l^* = D_{0, m(0)+1}$, $z_j^* = 0$, $l < j \leq m(0)+1$.

Hence $F_{m(0)+1} = C_{0, m(0)+1}^* + F_0$ express the minimal total inventory for $t = m(0)+1$ periods. Let now t be any period and the statement true for any period smaller than t . If F_t is not equal the minimal total inventory then there is some period $k < t$ such that

$$F_k + C_{k-1,t} < F_{i(t)} + C_{i(t)-1,t}^*. \quad (31)$$

Then, however $C_{k-1,t} = C_{k-1,i_l} + C_{i_l-1,t}^*$ and $F_k + C_{k-1,i_l} = F_{i_l}$ holds. The latter relation leads to a contradiction to the assumption (31). \square

4. Conclusions

A special dynamic production and inventory model has been studied in this paper. Apart from the mainstream of lot-size modeling here logical restrictions to keep the lot size on an accepted minimal level will contribute to set up an efficient production plan. The detailed analysis of the model allowed formulating a rather simple solution procedure. Like in the classical lot-sizing theory generalizations of the model will lead to NP-hard problems, but there is yet a hope to find efficient solutions for models with an upper bound of the lot size.

Tab. 4: Dynamic programming

$m=7, t=$	1	2	3	4	5	$F_t+C_{i-1,t}$	F_t
D_t	6	6	6	11	6	-	-
z_t	12	0					
I_t	6	0				0+6	6
z_t	7	11	0				
I_t	1	6	0			0+7	7
z_t	7	7	15	0			
I_t	1	2	11	0		0+14	
z_t			7	10			
I_t			1	0		6+1	7
z_t	7	7	7	14	0		
I_t	1	2	3	6	0	0+12	
z_t			7	16	0		
I_t			1	6	0	6+7	
z_t				17	0		
I_t				6	0	7+6	13

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